



01 Jan 1984

Correction to "Two-Dimensional Markov Representations of Sampled Images"

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Recommended Citation

J. A. Stuller, "Correction to "Two-Dimensional Markov Representations of Sampled Images"," *IEEE Transactions on Communications*, vol. 32, no. 6, p. 744, Institute of Electrical and Electronics Engineers, Jan 1984.

The definitive version is available at <https://doi.org/10.1109/TCOM.1984.1096115>

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$r_1 = r_2$, we have found that the optimal p that minimizes the total average delay is always 1. From the steady-state condition, it is easy to see that when $r_1 = r_2 = r$, the total arrival rate γ ($\gamma = 2r$) should be less than $2/3$ for steady state. In Fig. 5, the minimal total average delay (i.e., $p = 1$) is plotted versus γ when $r_1 = r_2$ for the access scheme of this paper (the acknowledgment-based access scheme), as well as for the random access scheme analyzed in [1]. As expected and as is shown in Fig. 5, the network performs much better with the access scheme analyzed in this paper. This latter result is actually correct for all values of arrival rates.

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Correction to "Two-Dimensional Markov Representations of Sampled Images"

J. A. STULLER

A representation for a sequence $\{x_i\}$ of N^2 arbitrarily scanned image intensity samples was sought in the above paper¹ such that each sample x_i , $1 \leq i \leq N^2$ is given as a linear combination of the preceding x_{i-1} , x_{i-2} , ..., x_1 plus an orthogonal random variable (r.v.) w_i . That is,

$$\mathbf{x} = L\mathbf{x} + \mathbf{w} \quad (1)$$

and

$$E\{x_i w_j\} = 0, \quad j < i \quad (2)$$

where \mathbf{x} is the N^2 element vector of the x_i , \mathbf{w} is the N^2 element vector of the w_i , and L is strictly lower triangular (entries on and above the principal diagonal equal zero). The paper related this one-sided representation to a two-sided representation in which each x_i , $1 \leq i \leq N^2$ is given as a linear combination of x_j , $j \neq i$, $1 \leq j \leq N^2$ plus an orthogonal r.v.

Paper approved by the Editor for Signal Processing and Communication Electronics of the IEEE Communications Society for publication without oral presentation. Manuscript received December 7, 1982; revised January 24, 1984.

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¹ J. A. Stuller and B. Kurz, *IEEE Trans. Commun.*, vol. COM-24, pp. 1148-1152, 1976.

u_i . That is,

$$\mathbf{x} = H\mathbf{x} + \mathbf{u} \quad (3)$$

and

$$E\{x_i u_j\} = 0, \quad j \neq i \quad (4)$$

where \mathbf{u} is the N^2 element vector of the u_i and H has a principal diagonal zero. An error occurred in the assumption that $\{w_i\}$ and $\{u_i\}$ are necessarily stationary. For an arbitrary scanning path over the $N \times N$ image raster, (9) and (13) of the above paper¹ should read

$$K_{xu} = E\{\mathbf{x}\mathbf{u}^T\} = D_u^{-2} \quad (5)$$

and

$$K_w = E\{\mathbf{w}\mathbf{w}^T\} = D_w^{-2} \quad (6)$$

where $D_u = \text{diag}[\sigma_{u_i}]$ and $D_w = \text{diag}[\sigma_{w_i}]$. This correction can be easily incorporated into the above paper¹ by representing \mathbf{u} and \mathbf{w} throughout as $\mathbf{u} = D_u \mathbf{u}_0$ and $\mathbf{w} = D_w \mathbf{w}_0$, with $E\{\mathbf{u}_0 \mathbf{u}_0^T\} = E\{\mathbf{w}_0 \mathbf{w}_0^T\} = I$, the $N^2 \times N^2$ identity matrix. Equations (10) and (11) of the above paper¹ then become, respectively,

$$K_u = (I - H)D_u^{-2} \quad (7)$$

and

$$\begin{aligned} K_x &= (I - H)^{-1} D_u^{-2} \\ &= D_u^{-2} K_u^{-1} D_u^{-2}. \end{aligned} \quad (8)$$

On combining (7) and (8) above, one has

$$(I - H) = D_u^{-2} K_x^{-1}. \quad (9)$$

All entries on the principal diagonal of H are zero. Therefore, all elements on the diagonal of $D_u^{-2} K_u^{-1}$ are unity. This implies that

$$\sigma_{u_i}^{-2} = \frac{1}{\gamma_i}, \quad i = 1, 2, \dots, N^2 \quad (10)$$

where γ_i is the i th element on the principal diagonal of K_x^{-1} . The orthogonality condition (4) implies that H is the LLMSE interpolator and $\sigma_{u_i}^{-2}$ is the interpolation error.

Similarly, (16) of the above paper¹ becomes

$$BK_x B^T = D_w^{-2} \quad (11)$$

and a unique lower triangular $B \triangleq I - L$ can be determined with unit diagonal [1]. Since L is strictly lower triangular, the orthogonality condition (2) implies that it is the LLMSE predictor and $\sigma_{w_i}^{-2}$ is the interpolation error.

The relation between the matrices H and L in the general case is

$$H = I - D_u^{-2} (I - L)^T D_w^{-2} (I - L). \quad (12)$$

ACKNOWLEDGMENT

The comments of a very competent reviewer resulted in an improvement in this correspondence.

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